

## Model predictive control

### General Information

**Number of ECTS Credits**

3

**Module code**

TSM\_PredContr

**Valid for academic year**

2020-2021

**Last modification**

2019-08-31

**Responsible of module**

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**Explanations regarding the language definitions for each location:**

- Instruction is given in the language defined below for each location/each time the module is held.
- Documentation is available in the languages defined below. Where documents are in several languages, the percentage distribution is shown (100% = all the documentation).
- The examination is available 100% in the languages shown for each location/each time it is held.

	Berne	Lausanne	Lugano	Zurich
<b>Instruction</b>				X E 100%
<b>Documentation</b>				X E 100%
<b>Examination</b>				X E 100%

**Module Category**

TSM Technical scientific module

**Lessons**

2 lecture periods and 1 tutorial period per week

### Entry level competences

**Prerequisites, previous knowledge**

- Linear Algebra
- Differential equations
- Basic feedback control and dynamic systems
- Basic programming skills in Matlab or Python or equivalent
- General affinity to mathematics(!)

## Brief course description of module objectives and content

Model Predictive Control (MPC) is an optimisation-based approach to control systems and processes. The general mathematical formulation of MPC allows it to be applied to a broad range of systems and considers system constraints intrinsically. The advances in optimisation methods and available computational power have made MPC a valuable alternative to classical control approaches also for fast dynamic systems. Today, MPC applications can be found from the original chemical process control systems to the control of frequency converters with sampling periods down to a few microseconds.

This module focuses on introducing MPC from the theoretical basics to the use of tool kits to support the implementation and generation of working code. As the classical frequency domain control methods are not considered here, this module does not need in-depth knowledge of control systems. A general affinity to mathematics and programming skills are beneficial.

## Aims, content, methods

### Learning objectives and acquired competencies

The student is able to

- formulate an optimisation problem and solve it with appropriate tool kits
- formulate model predictive control problems
- apply MPC concepts to real world systems and generate executable code which runs on their control systems

### Contents of module with emphasis on teaching content

Basic concepts ( 3W)

- Introduction to state space models in continuous and discrete time
- Introduction to optimisation (linear quadratic programs) using tool kits like YALMIP
- Introduction to optimisation with constraints

Basic MPC (3W)

- MPC problem formulation
- Receding horizon concepts
- Limits of MPC

Real-time implementation(3W)

- From problem to code using tool kits like ACADO

MPC Extensions and examples (5W)

- Reference tracking
- Buck converter control (explicit MPC)
- Nonlinear optimisation and MPC with nonlinear models
- Energy management (scheduling)

### Teaching and learning methods

Lectures with homework assignments which are a mix of theoretical exercises and programming assignments.

### Literature

## Assessment

### Certification requirements

Module uses certification requirements

### Certification requirements for final examinations (conditions for attestation)

Attendance of at least 9 tutorials.

### Basic principle for exams

**As a rule, all the standard final exams for modules and also all repetition exams are to be in written form**

### Standard final exam for a module and written repetition exam

Kind of exam

written

Duration of exam

120 minutes

**Permissible aids**

*Aids permitted as specified below:*

**Permissible electronic aids**

No electronic aids permitted

**Other permissible aids**

Open book

**Special case: Repetition exam as oral exam**

**Kind of exam**

oral

**Duration of exam**

30 minutes

**Permissible aids**

*Aids permitted as specified below:*

**Permissible electronic aids**

No electronic aids permitted

**Other permissible aids**

Open book